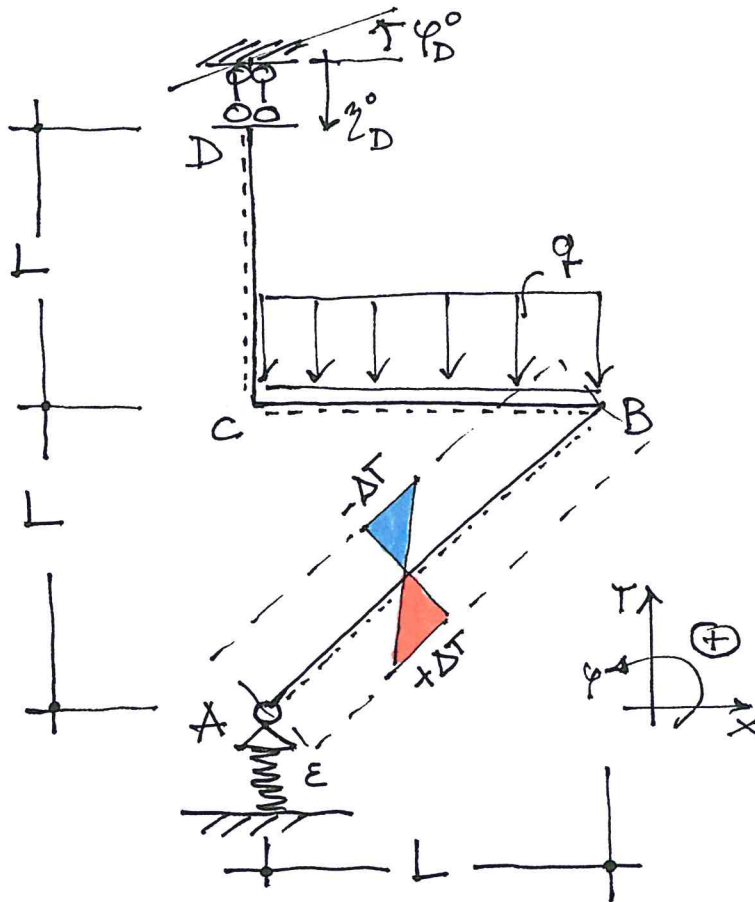


SOLUZIONE

Quesito n. 1

RISOLVERE LA STRUTTURA UNA VOLTA IPERSTATICA RIPORTATA IN FIGURA TRACCIANDO IL DIAGRAMMA DEI MOMENTI



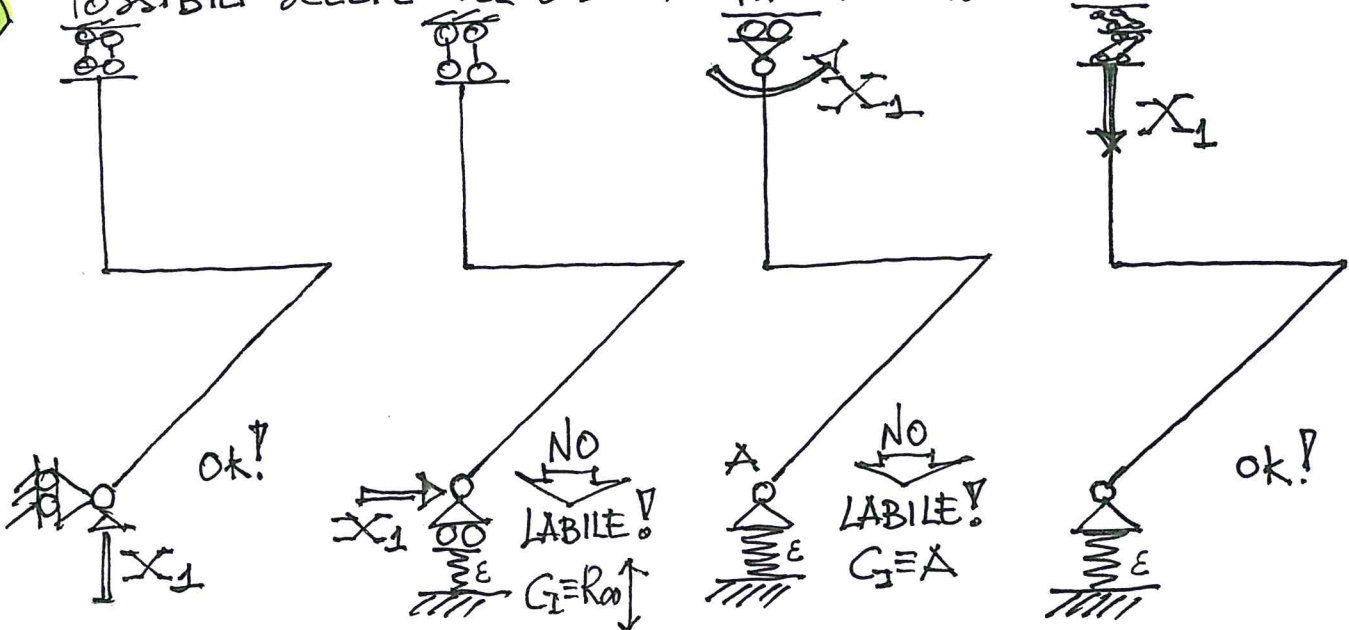
Posizioni:

$$|M_D^0| = \frac{qL^4}{24EI}$$

$$|\varepsilon| = \frac{L^3}{3EI} [\sqrt{2} + 1]$$

$$|\alpha \frac{\Delta T}{h}| = \frac{qL^2}{3EI} \frac{[\sqrt{2} + 1]}{\sqrt{2}}$$

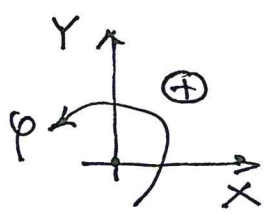
POSSIBILI SCELTE DEL SISTEMA PRINCIPALE ISOSTATICO:



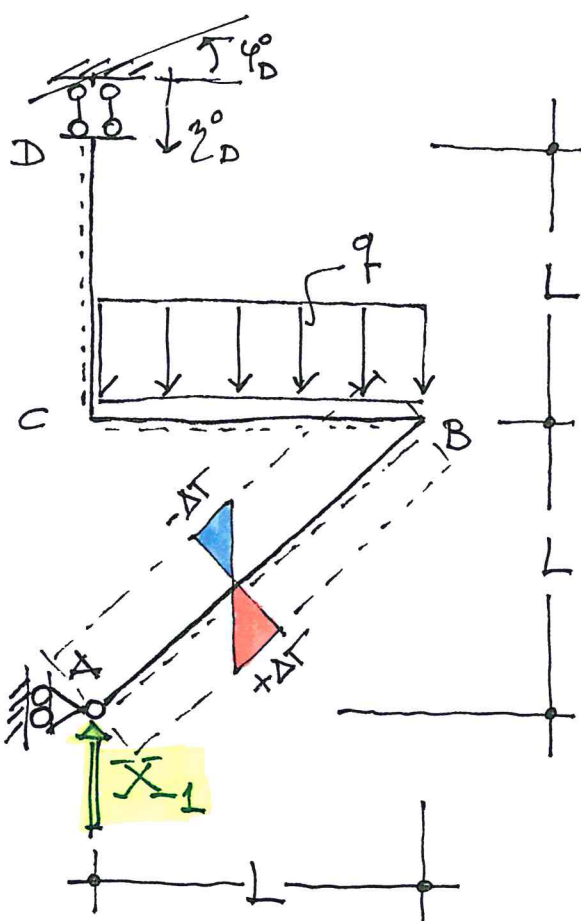
SOLUZIONE 1



SISTEMA
PRINCIPALE
ISOSTATICO

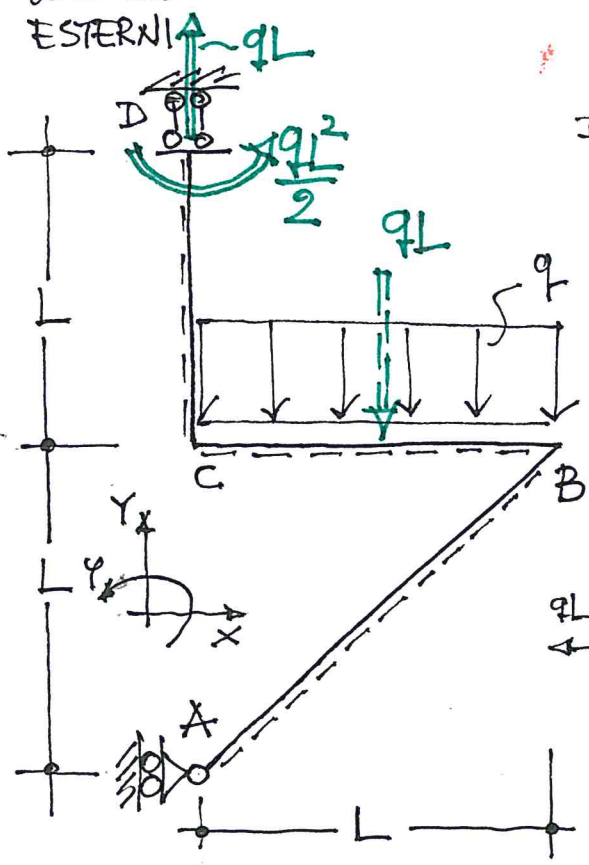


$$\eta_A = -E R_y^{(r)} = -E X_1$$



SCHEMA [0]

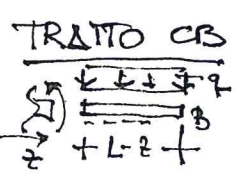
SOLO CARICHI
ESTERNI



I. Si calcolano
RV con metodo grafico! ... vedi figure!

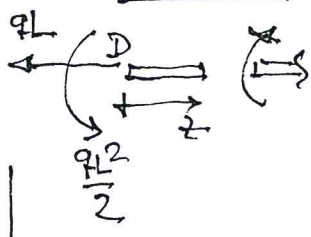
II. Si calcola $M^{(0)}(z)$ sui singoli tratti, si ha:

TRATTO AB \rightarrow scarico!



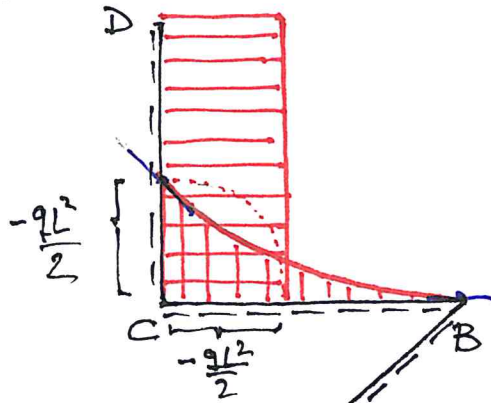
$$\begin{aligned} & 0 \leq z \leq L \\ & M^{(0)}(z) = -\frac{q(L-z)^2}{2} \end{aligned} \quad \left\{ \begin{aligned} M_C &= -\frac{qL^2}{2} \\ M_B &= 0 \end{aligned} \right.$$

TRATTO DC $0 \leq z \leq L$



$$M^{(0)}(z) = -\frac{qL^2}{2}$$

Diagramma $M^{(0)}(z)$:



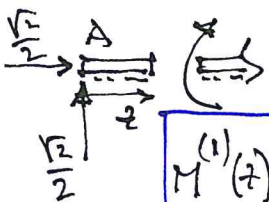
Schema [1]

Solo $X_1 = 1$

I. Si calcolano le RV con metodo grafico!... immediate!

II. Si calcola $M^{(1)}(z)$ sui supoli tratti, si ha:

TRATTO AB $0 \leq z \leq L\sqrt{2}$



$$M^{(1)}(z) = \frac{\sqrt{2}}{2} \cdot z \begin{cases} M_A = \phi \\ M_B = \frac{\sqrt{2}}{2} \cdot L\sqrt{2} = L \end{cases}$$

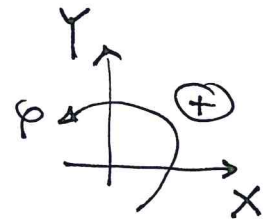
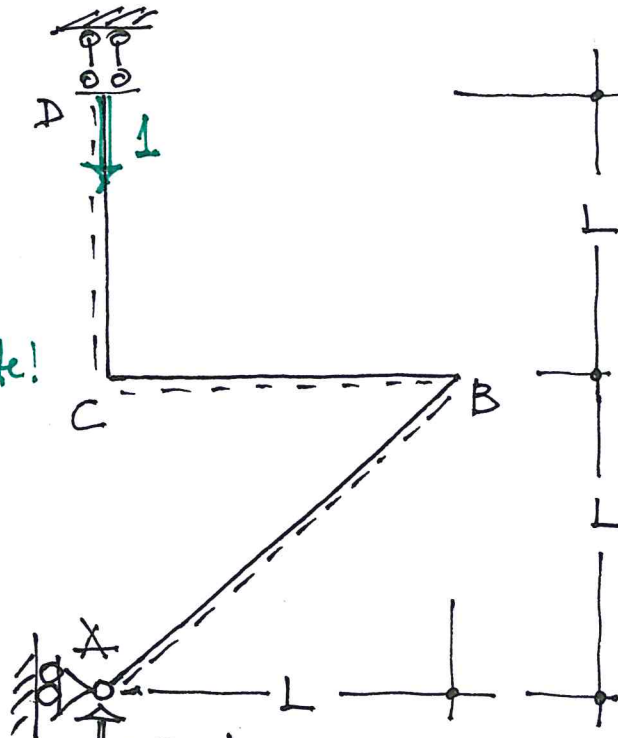
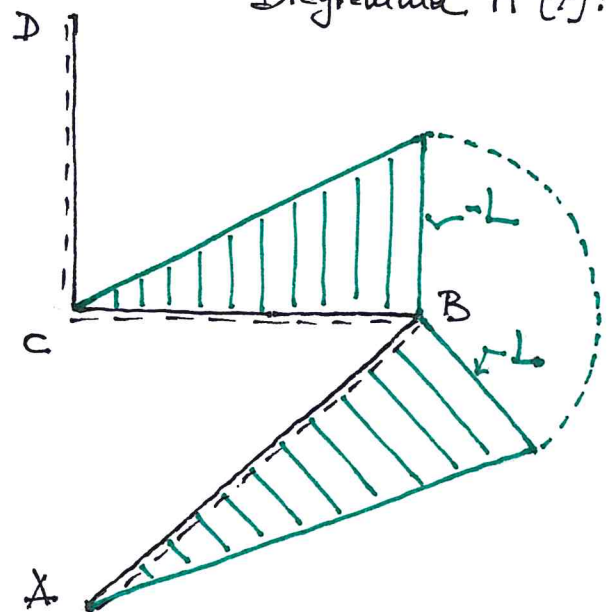
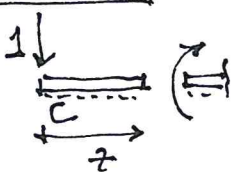


Diagramma $M^{(1)}(z)$:



TRATTO CB $0 \leq z \leq L$



$$M^{(1)}(z) = -z \begin{cases} M_C = \phi \\ M_B = -L \end{cases}$$

TRATTO BC $0 \leq z \leq L$

senso!! (solo N)



L'unica equazione di Müller-Breslau, corrispondente all'unica incognita iperstatica X_1 , si scrive nella forma

$L_{ve} = L_{vi}$ assumendo come sistema laminare o fisso lo schema [1] e come sistema reale la struttura iperstatica data.

Si ha:

$$L_{ve} = \sum_{i=1}^n X_i^{(f)} \cdot \eta_i^{(r)} + \sum_j R_j^{(f)} \eta_j^{(r)} =$$

$$= 1 \cdot \underbrace{\eta_A^{(r)}}_{-\varepsilon R_{y_A}^{(r)}} + \underbrace{M_D^{(1)}}_{\emptyset} \underbrace{\eta_D^{(0)}}_{\emptyset} + \underbrace{R_{y_D}^{(1)}}_{-1} \underbrace{\eta_D^{(0)}}_{\substack{<0 \\ \text{verso il} \\ \text{basso}}} = -\varepsilon X_1 + \eta_D^{(0)}$$

$$L_{vi} = \int_{str} M^{(f)} \frac{\eta^{(r)}}{EI} dstr + \int_{str} M^{(f)} \frac{\alpha \bar{\Delta T}}{h} dstr =$$

$\downarrow M^{(f)} = M^{(1)}$
 $\rightarrow M^{(r)} = M^{(0)} + M^{(1)} X_1$

$$= \int_{str} M^{(1)} \frac{M^{(0)}}{EI} dstr + X_1 \int_{str} \frac{[M^{(1)}]^2}{EI} dstr + \int_{str} M^{(1)} \frac{\alpha \bar{\Delta T}}{h} dstr =$$

$$= \frac{1}{EI} \left\{ \int_{CB}^{L} [-z] \left[-\frac{q}{2} (L-z)^2 \right] dz \right\} +$$

$$+ \frac{X_1}{EI} \left\{ \int_{AB}^{L} \left[\frac{\sqrt{2}}{2} z \right]^2 dz + \int_{CB}^{L} [-z]^2 dz \right\} + \frac{\alpha \bar{\Delta T}}{h} \int_{AB}^{L} \frac{\sqrt{2}}{2} z dz =$$

$$= \frac{1}{EI} \left\{ \int_0^L \left(\frac{q}{2} L^2 z + \frac{q}{2} z^3 - qLz^2 \right) dz \right\} +$$

$$+ \frac{X_1}{EI} \left\{ \int_0^{\frac{L\sqrt{2}}{2}} \frac{1}{2} z^2 dz + \int_0^L z^2 dz \right\} + \frac{\alpha \bar{\Delta T}}{h} \frac{\sqrt{2}}{2} \int_0^{L\sqrt{2}} z dz =$$

$$\begin{aligned}
 &= \frac{1}{EI} \left\{ \frac{qL^2}{2} \left[\frac{z^2}{2} \right]_0^L + \frac{q}{2} \left[\frac{z^4}{4} \right]_0^L - qL \left[\frac{z^3}{3} \right]_0^L \right\} + \\
 &\quad + \frac{X_1}{EI} \left\{ \frac{1}{2} \left[\frac{z^3}{3} \right]_0^{L\sqrt{2}} + \left[\frac{z^3}{3} \right]_0^L \right\} + \frac{\alpha \bar{\Delta T} \sqrt{2}}{h} \left[\frac{z^2}{2} \right]_0^{L\sqrt{2}} = \\
 &= \frac{1}{EI} \left\{ \frac{qL^4}{4} + \frac{qL^4}{8} - \frac{qL^4}{3} \right\} + \frac{X_1}{EI} \left\{ \frac{L^3 \sqrt{2}}{3} + \frac{L^3}{3} \right\} + \frac{\alpha \bar{\Delta T} \cdot \sqrt{2}}{h} \cdot \frac{L^2}{2} = \\
 &= \frac{qL^4}{EI} \cdot \frac{1}{24} + \frac{X_1 L^3}{3EI} [\sqrt{2} + 1] + \frac{\alpha \bar{\Delta T} \cdot \sqrt{2}}{h} \cdot \frac{L^2}{2}
 \end{aligned}$$

➡ In definitiva $L_{re} = L_{ri}$ fornisce:

$$-EX_1 + \eta_D^0 = \frac{qL^4}{24EI} + \frac{X_1 L^3}{3EI} [\sqrt{2} + 1] + \frac{\alpha \bar{\Delta T} \cdot \sqrt{2}}{h} \cdot \frac{L^2}{2}$$

quest'ultima, tenendo conto delle posizioni iniziali, si scrive:

$$-X_1 \cdot \frac{2L}{3EI} [\sqrt{2} + 1] + \frac{qL^4}{24EI} = \frac{qL^4}{24EI} + \frac{qL^2}{3EI} \frac{[\sqrt{2} + 1]}{\sqrt{2}} \cdot \frac{\sqrt{2}}{2} L$$

da cui: $X_1 = -\frac{qL}{4}$ ➡ **NEGATIVA!**

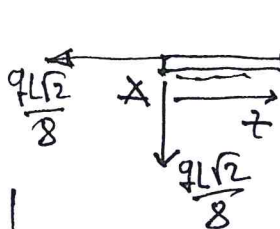
➡
Verso effettivo
CONTRARIO A
QUELLO INDICATO! CHE ERA
VERSO L'ALTO! quindi ESSA
VALE $\frac{qL}{4}$ VERSO IL BASSO!

**SOLUZIONE SISTEMA PRINCIPALE ISOSTATICO
E DIAGRAMMA $M^{(r)}(z)$ FINALE**

1. RV con metodo grafico e principio di sovrapp. degli effetti!

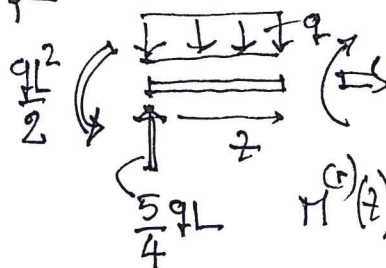
2. Calcolo di $M^{(r)}(z)$ sui supporti dati:

TRATTO AB $0 \leq z \leq L\sqrt{2}$



$$M^{(r)}(z) = -\frac{qL\sqrt{2}}{8} \cdot z \begin{cases} M_A = 0 \\ M_B = -\frac{qL^2}{4} \end{cases}$$

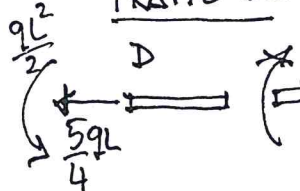
TRATTO CB $0 \leq z \leq L$



$$M^{(r)}(z) = \frac{5qL}{4} \cdot z - \frac{qz^2}{2} - \frac{qL^2}{2}$$

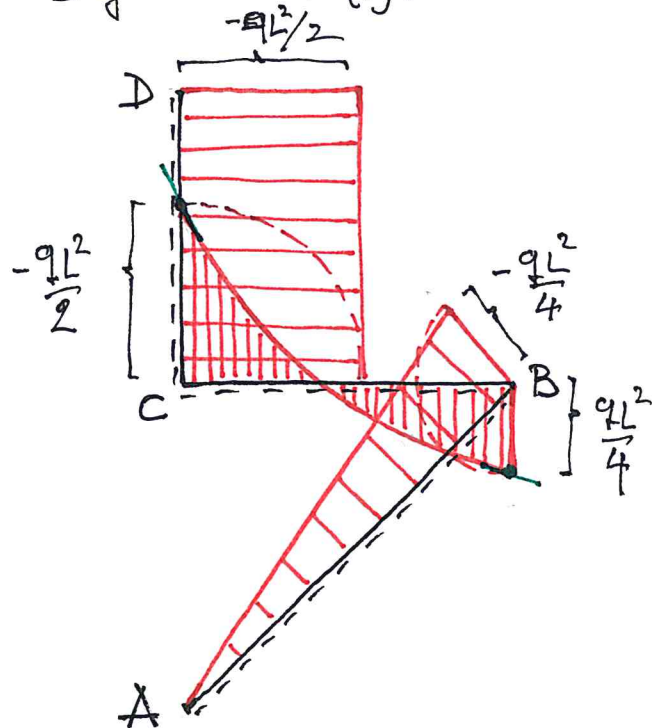
$$\begin{cases} M_C = -\frac{qL^2}{2} \\ M_B = \frac{qL^2}{4} \end{cases}$$

TRATTO DC $0 \leq z \leq L$



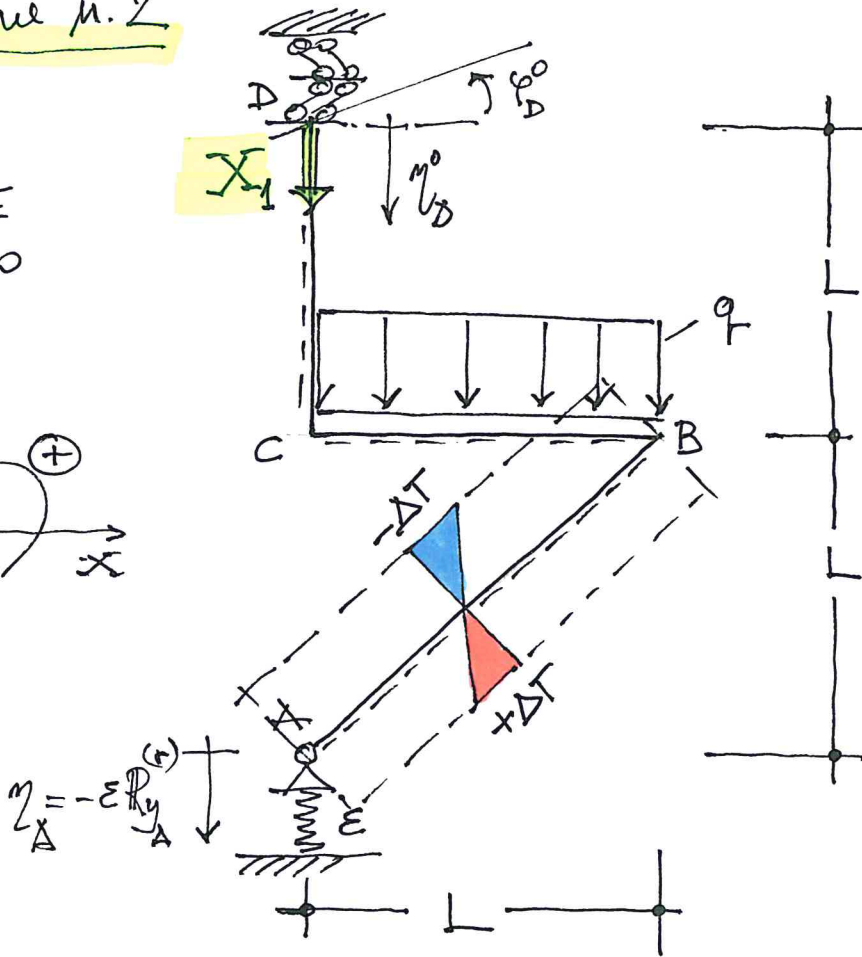
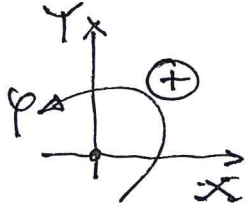
$$M^{(r)}(z) = -\frac{qL^2}{2}$$

Diagramma $M^{(r)}(z)$:

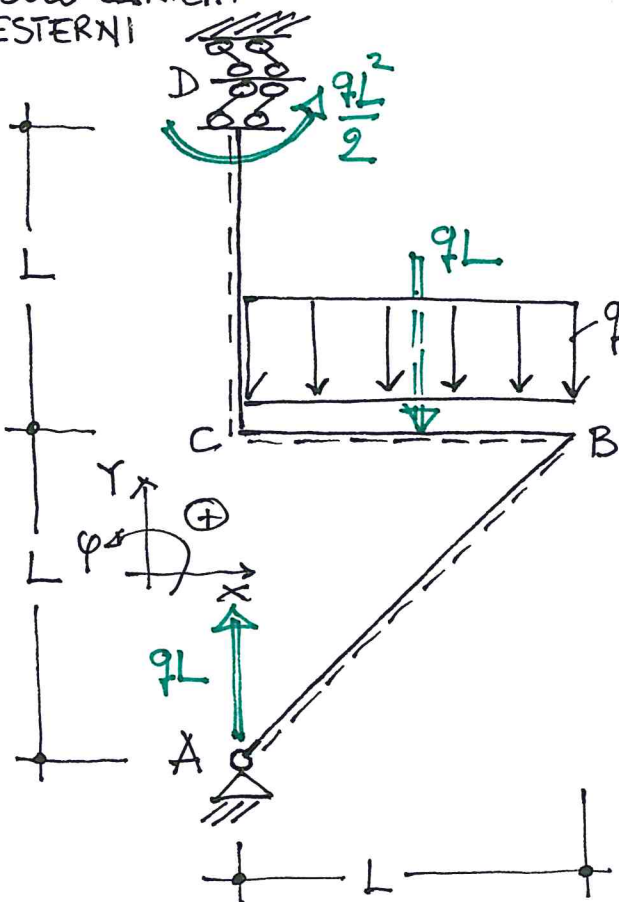


Soluzione n. 2

SISTEMA
PRINCIPALE
ISOSTATICO



SCHEMA [0]
SOLO CARICHI
ESTERNI



I. Si calcolano le RV con metodo
grafico ... vedi figura!

II. Si calcola $M^{(0)}(z)$ sui singoli
tratti. Si ha:

TRATTO AB $0 \leq z \leq L/\sqrt{2}$

$$M^{(0)}(z) = \frac{qL\sqrt{2}}{2} \cdot z \quad \left[\begin{array}{l} M_A = 0 \\ M_B = qL^2 \end{array} \right]$$

TRATTO CB $0 \leq z \leq L$

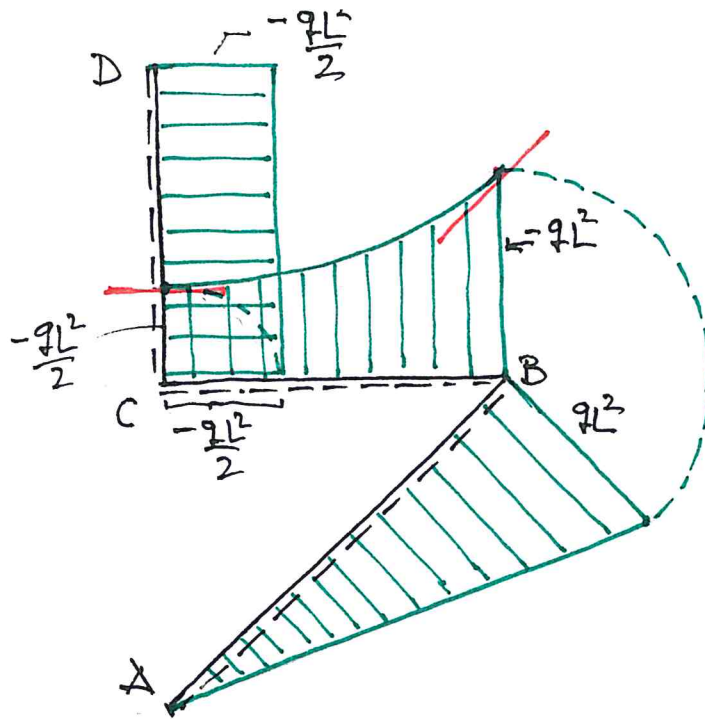
$$M^{(0)}(z) = -\frac{qL^2}{2} - \frac{qz^2}{2} \quad \left[\begin{array}{l} M_C = -\frac{qL^2}{2} \\ M_B = -qL^2 \end{array} \right]$$


TRATTO DC $0 \leq z \leq L$

$$M^{(0)}(z) = -\frac{qL^2}{2}$$

Diagramma $M^{(0)}(z)$

(VIII)
P. FUSCHI
A. PISANO

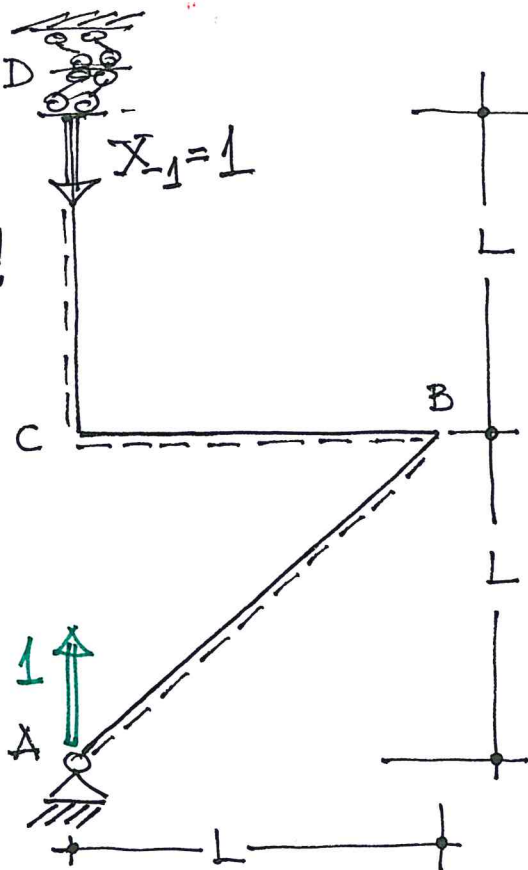
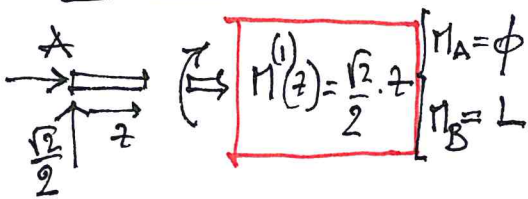


 SCHEMA [1]
Solo $X_1 = 1$

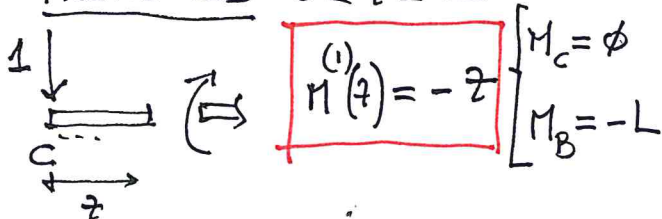
I. Si calcolano RV con metodo grafico!... immediate!

II. Si calcola $M^{(1)}(z)$ sui singoli tratti. Si ha:

TRATTO AB $0 \leq z \leq L/\sqrt{2}$



TRATTO CB $0 \leq z \leq L$



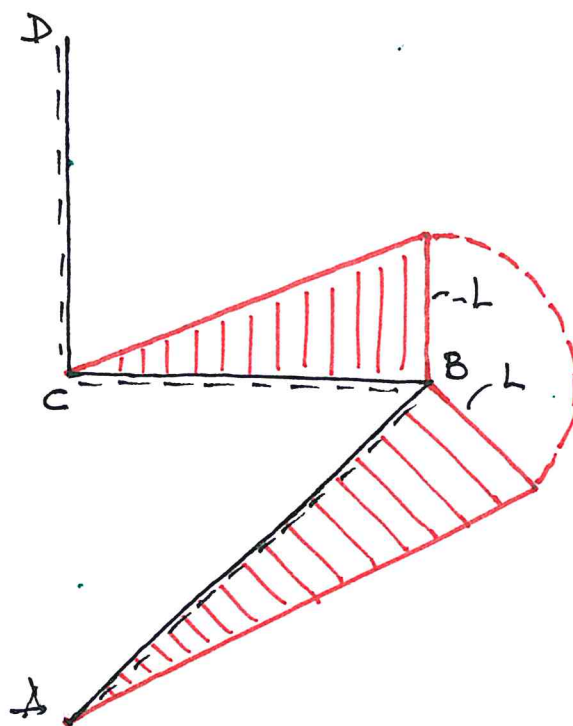
TRATTO DC $0 \leq z \leq L$

$$M^{(1)}(z) = 0$$

Diagramma $M^{(1)}(z)$:

IX

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A. PISANO



➔ L'unica equazione di Müller-Breslau, corrispondente all'unica incognita iperstatica X_1 , si scrive nella forma $L_{ve} = L_{vi}$ assumendo come sistema lavorante o fittizio lo schema [1] e come sistema reale la struttura iperstatica data. Si ha:

$$L_{ve} = X_1^{(f)} \cdot \eta_i^{(r)} + \int_j R_j^{(f)} \eta_j^{(r)} =$$

$$= (-1) \cdot (-\eta_D^0) + \underbrace{R_{yA}^{(1)}}_1 \cdot \underbrace{\eta_A^{(r)}}_{-\varepsilon R_{yA}^{(r)}} = \eta_D^0 - \varepsilon (qL + X_1)$$

$$\underbrace{R_{yA}^{(0)}}_{qL} + \underbrace{R_{yA}^{(1)}}_1 \cdot X_1$$

$$L_{vi} = \int_{Str} M^{(f)} \frac{\pi^{(r)}}{EI} dStr + \int_{Str} \pi^{(f)} \frac{\alpha \bar{\Delta T}}{h} dStr =$$

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A. PISANO

(X)

$$= \int_{Str} \pi^{(u)} \frac{\pi^{(e)}}{EI} dStr + X_1 \int_{Str} \frac{[\pi^{(u)}]^2}{EI} dStr + \int_{Str} \pi^{(u)} \frac{\alpha \bar{\Delta T}}{h} dStr =$$

$$= \frac{1}{EI} \left\{ \int_{AB} \left[\frac{\sqrt{2}}{2} z \right] \cdot \left[\frac{qL\sqrt{2}}{2} z \right] dz + \int_{CB} [-z] \left[-\frac{qL^2}{2} - \frac{qz^2}{2} \right] dz \right\} +$$

$$+ \frac{X_1}{EI} \left\{ \int_{AB} \left(\frac{\sqrt{2}}{2} z \right)^2 dz + \int_{CB} [-z]^2 dz \right\} + \int_{AB} \frac{\sqrt{2}}{2} z \frac{\alpha \bar{\Delta T}}{h} dz =$$

$$= \frac{1}{EI} \left\{ \int_0^{L\sqrt{2}} \frac{qL}{2} z^2 dz + \int_0^L \left(\frac{qL^2}{2} z + \frac{q}{2} z^3 \right) dz \right\} +$$

$$+ \frac{X_1}{EI} \left\{ \int_0^{L\sqrt{2}} \frac{1}{2} z^2 dz + \int_0^L z^2 dz \right\} + \frac{\alpha \bar{\Delta T}}{h} \frac{\sqrt{2}}{2} \int_0^{L\sqrt{2}} z dz =$$

$$= \frac{1}{EI} \left\{ \frac{qL}{2} \left[\frac{z^3}{3} \right]_0^{L\sqrt{2}} + \frac{qL^2}{2} \left[\frac{z^2}{2} \right]_0^L + \frac{q}{2} \left[\frac{z^4}{4} \right]_0^L \right\} +$$

$$+ \frac{X_1}{EI} \left\{ \frac{1}{2} \left[\frac{z^3}{3} \right]_0^{L\sqrt{2}} + \left[\frac{z^3}{3} \right]_0^L \right\} + \frac{\alpha \bar{\Delta T}}{h} \frac{\sqrt{2}}{2} \left[\frac{z^2}{2} \right]_0^{L\sqrt{2}} =$$

$$= \frac{1}{EI} \left\{ \frac{qL^4\sqrt{2}}{3} + \frac{qL^4}{4} + \frac{qL^4}{8} \right\} + \frac{X_1}{EI} \left\{ \frac{\sqrt{2}}{3} L^3 + \frac{L^3}{3} \right\} + \frac{\alpha \bar{\Delta T}}{h} \frac{\sqrt{2}}{2} L^2 =$$

$$= \frac{qL^4\sqrt{2}}{3EI} + \frac{3}{8} \frac{qL^4}{EI} + \frac{X_1 L^3}{3EI} [\sqrt{2} + 1] + \frac{\alpha \bar{\Delta T}}{h} \frac{\sqrt{2}}{2} L^2$$

➔ In definitiva $L_{re} = L_{ri}$ fornisce:

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A. PISANO

$$\eta_D^0 - \varepsilon [qL + X_1] = \frac{qL^4}{3EI} \sqrt{2} + \frac{3}{8} \frac{qL^4}{EI} + \frac{X_1 L^3}{3EI} [\sqrt{2} + 1] + \alpha \frac{\Delta T}{h} \frac{\sqrt{2}}{2} L^2$$

quest'ultima, tenendo conto delle posizioni iniziali, si scrive:

$$\frac{qL^4}{24EI} - \frac{L^3}{3EI} [\sqrt{2} + 1] [qL + X_1] = \frac{qL^4}{3EI} \sqrt{2} + \frac{3}{8} \frac{qL^4}{EI} + \frac{X_1 L^3}{3EI} [\sqrt{2} + 1] + \frac{qL^2}{3EI} \frac{[\sqrt{2} + 1]}{\sqrt{2}} \cdot \frac{\sqrt{2}}{2} L^2$$

e ancora:

$$\frac{qL^4}{24EI} - \frac{L^3}{3EI} [\sqrt{2} + 1] qL - \frac{L^3}{3EI} [\sqrt{2} + 1] X_1 = \frac{qL^4}{3EI} \sqrt{2} + \frac{3}{8} \frac{qL^4}{EI} + \frac{X_1 L^3}{3EI} [\sqrt{2} + 1] + \frac{qL^4 [\sqrt{2} + 1]}{6EI}$$

quest'ultima, semplificando ulteriormente, fornisce:

$$-\frac{5}{6} qL^4 [\sqrt{2} + 1] = \frac{2}{3} L^3 [\sqrt{2} + 1] X_1$$

e, in definitiva, si ha:

$$X_1 = -\frac{5}{4} qL$$

➔ **NEGATIVA!** ➔

VERSO OPPOSTO
A QUELLO
IPOTIZZATO! ESSA È
CIDE' VERSO L'ALTO!

OK! ➔

cf. con la R.V.
di pag VI ottenuta
in precedente!